THE CUMULATIVE DISTANCE FROM AN OBSERVED TO A STABLE AGE STRUCTURE*

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Abstract. In a closed, unisexual, age-structured population with age-specific birth and death rates which are constant in time, the vector describing a census by age categories will, as time increases, approach proportionality to the stable age structure implied by the vital rates. This stable age structure is the dominant eigenvector of a demographic projection matrix which carries out the action on a census vector of the age-specific vital rates. We show that the elementwise convergence to zero of the discounted deviations from the stable age structure is complete and exponential. The sum, over all time, of the signed discounted deviations may be easily calculated from a fundamental matrix based on the projection matrix. These results are proved for any primitive nonnegative square matrix. In the demographic context, these results suggest alternatives to an index which has been used to measure the distance from an observed to a stable age structure.

1. Introduction and results. The theory of stable populations considers closed, unisexual, age-structured populations. Individuals are subject to birth and death rates which depend on age and are constant in time (Keyfitz [8], Coale [2]). Suppose time and age are measured in the same discrete unit. Let \( K \) be a census vector, that is, a nonnegative, nonzero column \( n \)-vector giving the number of individuals in each of \( n \) age classes at the present time, taken as \( t = 0 \). Let \( M \) be an \( n \times n \) projection matrix. The \( i, j \)th element of \( M \) measures the contribution to age class \( i \) at time \( t + 1 \) of one individual in age class \( j \) at time \( t \). We assume only that \( M \) is nonnegative and primitive (i.e. that every element of \( M^t \) is positive, for some \( t \)). These assumptions hold for at least every observed human population if age classes beyond the last age of reproduction are excluded. It is a well-known consequence of the Perron–Frobenius theorem that \( M \) has a simple real root (eigenvalue) \( \lambda \) with modulus larger than the modulus of every other root and that

\[
\lim_{t \to \infty} \lambda^{-t}M^t = B
\]

where \( B \) is a finite positive \( n \times n \) matrix. Consequently if

\[
K(t) = M^tK, \quad t = 0, 1, 2, \ldots
\]

is the result of projecting the census vector \( K \) forward \( t \) time units via \( M \), then, as the strong ergodic theorem of demography observes,

\[
\lim_{t \to \infty} \lambda^{-t}[(K(t) - \lambda^tBK)] = 0.
\]

The zero on the right of (3) is an \( n \)-vector with each element zero.

Let the sum of the first \( t \) terms of the sequence on the left of (3) be

\[
S_t(M, K) = \sum_{m=0}^{t-1} \lambda^{-m}M^mK - tBK, \quad t = 1, 2, \ldots
\]
We shall show that the terms in (3) approach 0 so rapidly that the sequence of sums in (4) approaches a finite limit as $t \to \infty$. This limit may be calculated directly:

$$\lim_{t \to \infty} S_i(M, K) = (Z - B)K$$

where

$$Z = (I + B - M/\lambda)^{-1}.$$  

We shall prove that $Z$ exists and satisfies (5). Moreover, the total number of individuals in age class $i$ at time $t$ resulting from an initial population consisting of only one individual in age class $j$ and no others at time 0 is $M^{(t)}_{ij}$, the $i,j$th element of $M^t$, $i, j = 1, \ldots, n$, and

$$\lim_{t \to \infty} \sum_{i=1}^{n} \sum_{m=0}^{t-1} \lambda^{-m}M^{(t)}_{ii} - t = \sum_{i=1}^{n} z_{ii} - 1.$$  

Here $z_{ii}$ is the $i$th diagonal element of $Z$.

In the sequence of $n$-vectors in the brackets on the left of (3), the $i$th element may be sometimes positive, sometimes negative. Hence in the sums (4), the $i$th element may be the sum of positive and negative terms. The finiteness of the limiting sum does not depend on any cancellation of positive and negative terms. Specifically, let

$$R_i(M, K) = \sum_{m=0}^{t-1} \lambda^{-m}|M^mK - \lambda^mBK|, \quad t = 1, 2, \ldots,$$

where $|M^mK - BK|$ is an $n$-vector in which the $i$th element is the absolute value of the $i$th element of the $n$-vector $M^mK - BK$. We shall show that

$$\lim_{t \to \infty} R_i(M, K) < \infty.$$  

The limit in (9), and hence in (5), is approached exponentially fast. We know no simple exact expression for this limit, unlike the limit in (5).

If

$$k = K / \sum_{i=1}^{n} K_i$$

is the age structure associated with the census vector $K$, the observations (5) and (9) suggest that $\lim S_i(M, k)$ and $\lim R_i(M, k)$ provide natural scale-invariant vector measures of the cumulative distance from the age structure $k$ of the census $K$ to the stable age structure associated with $M$.

In the next section of this note, we verify the limits (5) and (9) with a numerical example. Based on these limits, we propose indexes to measure the departure of an observed from a stable age structure. We compare numerically the behavior of these indexes with that of an index of dissimilarity $\Delta$ used by Keyfitz [8, p. 47] and Keyfitz and Flieger [9] as a measure of the departure of an observed from a stable age structure.

The final section of this note proves the properties of $Z$ claimed in (5), (6), (7), the inequality (9), and some additional properties for nonnegative primitive matrices generally, without restriction to the form of population projection matrices.

### 2. Numerical illustration

The 1965 female population of the United States included $K_1 = 29,413$ thousand girls under 15; $K_2 = 20,886$ thousand women 15–29; and 18,040 thousand women 30–44 (Keyfitz [8, p. 56]). Using the same age categories
and a 15-year time unit, the projection matrix for this population, based on adjusted births, is (Keyfitz [8, p. 42])

\[
M = \begin{pmatrix}
0.4271 & 0.8498 & 0.1273 \\
0.9924 & 0 & 0 \\
0 & 0.9826 & 0
\end{pmatrix}.
\] (11)

All subsequent calculations, based on these data, have been carried out with 10 significant figures and rounded only for reporting. In the stable age structure \( k^* \) of \( M \), the three age classes would occur in the proportions \( k_1^* = 0.4020, k_2^* = 0.3299, k_3^* = 0.2681 \). The matrix \( B \) and growth rate \( \lambda \) are given correctly to the number of places shown by Keyfitz [8, p. 43; his \( Z_1 = \text{our } B \), his \( \lambda_1 = \text{our } \lambda \)]. From (6),

\[
Z = \begin{pmatrix}
0.8494 & 0.1607 & 0.0281 \\
0.2191 & 0.7551 & -0.0272 \\
-0.2103 & 0.3075 & 0.9370
\end{pmatrix}.
\] (12)

Direct computation from (4) and (8) gives \( S_t(M, K) \) and \( R_t(M, K) \) for \( t = 1, 2, \cdots, 18 \) (Table 1). \( S_t(M, K) \) shows a rapid damped oscillatory convergence to the limit \((Z - B)K\), which coincides with \( S_{16}(M, K) \) to the accuracy shown. As \( S_t(M, K) \) settles at \((Z - B)K\), \( R_t(M, K) \) ceases to change.

We now consider these limits as a basis for measures of the distance between an observed age structure \( k \) and its stable limit \( k^* \).

In a series of papers starting in 1955, O. Dudley Duncan and Beverly Duncan introduced into demography an index of dissimilarity \( \Delta \) to measure the difference between two age structures \( k \) and \( k' \). \( k \) and \( k' \) are nonnegative vectors, the elements of each of which sum to 1. \( \Delta \) is the sum of the positive differences of the percentages in each age class, which is equivalent to

\[
\Delta = \left(\frac{100}{2}\right) \sum_{i=1}^{n} |k_i - k'_i|.
\] (13)

This index was extensively used in studies of demographic segregation. For references to primary sources and applications, see Shryock and Siegel [12, I: 179, 232–233, 262]. Except for the factor 100 which converts from fractions to percentages, this index of dissimilarity is standard in probability theory as a measure of the difference between two probability measures (Loève [10, p. 367]).

Keyfitz [8, p. 47] and Keyfitz and Flieger [9] used \( \Delta \) to compare, not two different observed age structures, but an observed age structure \( k \) and its limiting stable age structure \( k^* \). For this purpose we suggest two alternative measures

\[
D_1 = 50 \sum_{i=1}^{n} |(Z - B)k)_i|,
\] (14)

where \(((Z - B)k)_i\) is the \( i \)th element of the \( n \)-vector \((Z - B)k\), and

\[
D_2 = 50 \sum_{i=1}^{n} \lim_{t \to \infty} |R_t(M, k)_i|.
\] (15)

The arbitrary numerical constant 50 is introduced solely in order to adjust these two indexes to a magnitude close to that of \( \Delta \).
For the 1965 female population of the United States, using the three age groups given, $\Delta = 2.8355$ when $k'$ is replaced by the stable age structure $k^*$, $D_1 = 2.5922$ and (taking $t = 25$ as a sufficient approximation to $\infty$) $D_2 = 9.0700$.

The reason for suggesting $D_1$ and $D_2$ becomes clearer if $a$, $D_1$ and $D_2$ are compared for the same $M$ and $k^*$, but in place of $k$, a plausible hypothetical age structure $k'$ with the proportions $k'_1 = 0.42$, $k'_2 = 0.30$, $k'_3 = 0.28$. Now $\Delta$ increases to 2.9905 but $D_1$ decreases to 1.5160 and $D_2$ decreases to 8.5280. The index $\Delta$ suggests that the observed $k = (0.4304, 0.3056, 0.2640)$ is closer to the stable $k^*$ than is the hypothetical $k'$, while $D_1$ and $D_2$ suggest the opposite.

$\Delta$ measures the distance from $k$ to $k^*$ as the demographic crow flies, without regard to the trajectory of age structures through which the population must pass as it approaches stability. Thus for a given $k$ and $k^*$, $\Delta$ would be the same regardless of the projection matrix, as long as the projection matrix had the same stable age structure $k^*$.

$D_1$ and $D_2$ are more like charts of the highway mileage or travel time between $k$ and $k^*$ since they cumulate over all time, with appropriate discounting, the signed or absolute discrepancies between $K(t)$ and the stable population. We suggest that for some purposes $D_1$ and $D_2$ may be demographically more meaningful indexes than $\Delta$.

$D_1$ and $D_2$ appear to depend on the number $n$ of age classes. For certain applications, such as comparisons across species, it might be desirable in the future to develop measures independent of $n$.

### Table 1

Cumulated signed and absolute differences between projections of the 1965 United States female population and the stable age distribution.

<table>
<thead>
<tr>
<th>Time $t$</th>
<th>$S_t(M, K)$ (in thousands)</th>
<th>$R_t(M, K)$ (in thousands)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Age group</td>
<td>Age group</td>
</tr>
<tr>
<td></td>
<td>0-14</td>
<td>15-29</td>
</tr>
<tr>
<td>1</td>
<td>1589</td>
<td>-1947</td>
</tr>
<tr>
<td>2</td>
<td>728</td>
<td>-643</td>
</tr>
<tr>
<td>3</td>
<td>1173</td>
<td>-1350</td>
</tr>
<tr>
<td>4</td>
<td>945</td>
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<tr>
<td>18</td>
<td>1022</td>
<td>-1108</td>
</tr>
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</table>

3. The fundamental matrix of a primitive matrix. Theorems 1 to 3 below generalize results known for the transition matrix of a regular Markov chain (Kemeny and Snell [7, pp. 75–77]) to any primitive nonnegative matrix $T$ with dominant eigenvalue $\lambda$. Theorem 4 may be new even in the context of regular Markov chains. The results claimed in the first part of this note follow by specializing $T$ to $M$. 
From Seneta [11, p. 7] and Karlin and Taylor [6, p. 546], it is known that there exists a positive matrix $B$ such that $\lim_{t \to \infty} (\lambda^{-1} T)^t - B = 0$. For any integer $t > 0$, $B^t = B$. For some positive column vector $x$ such that $Tx = \lambda x$ and for some positive row vector $w^T$, $w^T x = 1$ and $xw^T = B$. (Throughout, the superscript $T$ means transpose.) Also $TB = BT = AB$.

**Theorem 1.** $Z = (I + B - \lambda^{-1} T)^{-1}$ exists and is given by

$$Z = I + \sum_{t=1}^{\infty} ([\lambda^{-1} T]^t - B).$$

The proof repeats the proof of Theorem 4.3.1 of Kemeny and Snell [7, p. 75] step for step, with $\lambda^{-1} T$ replacing their stochastic matrix $P$.

To obtain (5) from Theorem 1, subtract $B$ from both sides of (16) and multiply both sides on the right by $K$.

By analogy with the convention in the theory of Markov chains, we call $Z$ the fundamental matrix of the primitive matrix $T$. $Z$ has properties which may prove useful.

**Theorem 2.** With $T$, $x$, $Z$, $A$, and $B$ as above,

(a) $TZ = ZT$,
(b) $Zx = x$,
(c) $I - Z = B - \lambda^{-1} T$.

The proof repeats the steps of the proof of Theorem 4.3.3 of Kemeny and Snell [7, pp. 75-76]. Contrary to Theorem 4.3.3(b) in [7], when $\lambda^{-1} T$ is not a stochastic matrix, the row sums of $Z$ are not in general 1, as the example of $Z$ in (12) shows.

If $T$ is of rank 1, then $Z = I$. The proof is that if $T$ is primitive and of rank 1 with positive eigenvector $x$ corresponding to $\lambda$, then for some positive $n$-vector $y$, $T = xy^T$. Then $\lambda B = BT = (xw^T)(xy^T) = x(w^T x)y^T = T$, which implies $B = \lambda^{-1} T$. Thus $Z = (I + B - \lambda^{-1} T)^{-1} = T^{-1} = I$.

Recall that the trace of a matrix is the sum of the elements on its main diagonal. Thus $\text{trace}(B) = 1$. Let $T_{ij}^{(m)}$ be the $i$, $j$th element of $T^m$.

**Theorem 3.**

$$\lim_{t \to \infty} \sum_{m=0}^{t-1} \lambda^{-m} \text{trace}(T^m) - t = \text{trace}(Z) - 1.$$  

Equation (7) follows.

To prove Theorem 3, let $w_j$ be the $j$th element of $w$ (recall that $B = xw^T$). Then $(Z - B)w_j = z_{ij} - x_j w_i$. Summing over $j$ gives $\sum_{j=1}^{n} (Z - B)w_j = \sum z_{ij} - 1$. But from Theorem 1, $\lim_{t \to \infty} \sum_{j=1}^{n} \lambda^{-m} T_{ij}^{(m)} = c_i = (Z - B)w_i$. Again summing over $j$ and exchanging the limit with the finite sum gives (17). Eugene Seneta (personal communication) has another proof.

**Theorem 4.** There exist positive constants $a$ and $b$ such that

$$\lambda^{-m} |T_{ij}^{(m)} - \lambda^{-m} B_{ij}| \leq \alpha e^{-bm}, \quad m = 0, 1, 2, \ldots.$$  

Specifically, let $\lambda_2 \neq \lambda$ be an eigenvalue of $T$ whose modulus $|\lambda_2|$ is exceeded by the modulus of no eigenvalue of $T$ other than $\lambda$. If $|\lambda_2| > 0$, pick any $\varepsilon$ such that $0 < \varepsilon < \log(\lambda/|\lambda_2|)$. Then for some $a > 0$, $b = \log(\lambda/|\lambda_2|) - \varepsilon > 0$ satisfies (18).

(If $|\lambda_2| = 0$, $T$ is of rank 1 and $\lambda^{-1} T = B$, so the limit in (3) is attained as soon as $t = 1$. We therefore suppose $|\lambda_2| > 0$.)

To prove Theorem 4, let $f(m) = \lambda^{-m} |T_{ij}^{(m)} - \lambda^{-m} B_{ij}|$. Then we claim there exist positive constants $a$ and $b$ such that (18) holds if there exists an integer $m_0 \geq 0$ and positive constants $a'$ and $b'$ such that $f(m) \leq a' e^{-bm}$ for $m = m_0, m_0 + 1, \ldots$. To prove this, let $A = \max_{m=0, \ldots, m_0-1} f(m)$. $A$ is finite and positive. Choose $a = \max (A e^{-bm_0}, a')$. Then $a e^{-bm} \leq A \leq f(m)$ for $m = 0, 1, \ldots, m_0 - 1$ and $a e^{-bm} \leq a' e^{-bm}$ for $m =
Thus it suffices to find an exponentially decaying upper bound \( a^\prime e^{-bm} \) of \( f(m) \) which holds for all but at most a finite number \( m_0 \) of terms.

Let \( \lambda_2 \) be the eigenvalue with largest algebraic multiplicity in the minimal polynomial of \( T \) among those eigenvalues with modulus equal to \( |\lambda_2| \). We observe from the spectral decomposition of powers of a matrix (Gantmacher [3, 1:104, his eq. (17)]; Seneta [11, p. 7]) that \( T_i^{(m)} \) is a polynomial of some form constant \( \cdot m^s \lambda_\frac{m}{2}^m \) where \( \lambda_2 \) runs over the set of eigenvalues of \( T (\lambda_1 = \lambda) \), and \( s_0 \) runs from 0 up to one less than the multiplicity of \( \lambda_2 \) as a root of the minimal polynomial of \( T \) (\( s_1 = 0 \) only). Here the constant coefficient may absorb some power of \( \lambda_2 \), which is independent of \( m \). Thus \( T_i^{(m)} = \lambda^m B_i + cm^s \lambda_2^m + \) other terms of the form \( c'(m')^s \lambda_\frac{m}{2}^m \), \( h \geq 2 \), where if \( |\lambda_2| = |\lambda_2| \) then \( s' < s \). Thus \( f(m) = \lambda^{-m}|T_i^{(m)}| - \lambda^{-m}|B_i| \leq |c|m^s(|\lambda_2|/\lambda)^m + \) other terms of smaller magnitude (when \( m \) is large enough) than \( |c|m^s(|\lambda_2|/\lambda)^m \).

Now \( m^s(|\lambda|/\lambda)^m = a^* e^{-bm} \) if \( s \log m + m \log (|\lambda_2|/\lambda) \leq \log a^* - bm \) or \( s \log m \leq \log a^* - m(\log (|\lambda_2|/\lambda) + b) \). For \( m > 1 \), \( \log m > 0 \) and division by \( \log m \) preserves the sense of the last inequality, giving \( s \leq (\log a^*)/(\log m) - \log (|\lambda_2|/\lambda) + b)/\log m \). Choosing \( a^* = 1 \) and \( b = \log (|\lambda_2|/\lambda) - e > 0 \), the latest inequality certainly holds if \( s \leq em/\log m \), where \( e > 0 \), or if \( s/e \leq m/\log m \). It is well known that for any fixed \( s/e > 0 \), there exists an integer \( m_0 > 1 \) such that \( s/e \leq m/\log m \) for all \( m \geq m_0 \). If necessary, \( m_0 \) can be adjusted upward to assure that all remaining terms in the spectral expansion of \( T_i^{(m)} \) are of smaller magnitude than \( |c|m^s(|\lambda_2|/\lambda)^m \) for \( m \geq m_0 \). Then choose \( a^* \geq |c| \) to allow for these additional terms as well so that \( f(m) \leq a^* e^{-bm} \) for \( m \geq m_0 \). Given \( b, a^* \), and \( m_0 \), we may find the required constants \( a \) and \( b \).

From Theorem 4, (9) follows by summing (18) over \( m \) and multiplying by the census vector \( K \).

Birkhoff [1, Chap. 16] proved that the limiting eigenvector is approached exponentially fast in the Hilbert projective pseudo-metric under the action of a positive matrix. He also gave (his Corollary 2, p. 385) an explicit upper bound for \( |\lambda_\frac{m}{2}|/\lambda, h \geq 2 \). Golubitsky, Keeler and Rothschild [4] and Hajnal [5] greatly extended the conditions under which exponential convergence in the projective pseudo-metric holds. Theorem 4 and (9) prove complete exponential convergence of the absolute differences elementwise, rather than of the Hilbert projective pseudo-metric.

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